

# Package ‘SpatialGraph’

November 27, 2018

**Version** 1.0-2

**Type** Package

**Title** SpatialGraph Class

**Date** 2018-11-27

**Imports** igraph, methods, rgeos, shape, sp, splancs

**Author** Javier Garcia-Pintado

**Maintainer** Javier Garcia-Pintado <jgarciapintado@marum.de>

**Description** Provision of the S4 SpatialGraph class built on top of objects provided by 'igraph' and 'sp' packages, and associated utilities. See the documentation of the SpatialGraph-class within this package for further description. An example of how from a few points one can arrive to a SpatialGraph is provided in the function sl2sg().

**License** GPL (>= 2)

**URL** <https://github.com/garciapintado/SpatialGraph>

**NeedsCompilation** no

**Repository** CRAN

**Date/Publication** 2018-11-27 10:30:03 UTC

## R topics documented:

SpatialGraph-package . . . . .	2
attSGe . . . . .	3
distSGv . . . . .	4
explodeSLDF . . . . .	4
pointLineD . . . . .	5
pointOnLine . . . . .	6
pointOnSegment . . . . .	6
pointPolylineD . . . . .	7
pointsToLines . . . . .	8
polylineChainage . . . . .	9
polylineLength . . . . .	9
revSGe . . . . .	10

rotation . . . . .	11
routeSDG . . . . .	11
sg2igraph . . . . .	12
sgChVIDs . . . . .	12
sl2sg . . . . .	13
SpatialGraph . . . . .	14
SpatialGraph-class . . . . .	15
splitPolyline . . . . .	16
splitSLDF . . . . .	16
textSGe . . . . .	17

<b>Index</b>	<b>18</b>
--------------	-----------

---

SpatialGraph-package    *SpatialGraph Class*

---

## Description

Provision of the S4 SpatialGraph class built on top of objects provided by 'igraph' and 'sp' packages, and associated utilities. See the documentation of the SpatialGraph-class within this package for further description. An example of how from a few points one can arrive to a SpatialGraph is provided in the function sl2sg().

## Details

The DESCRIPTION file:

```

Package:      SpatialGraph
Version:      1.0-2
Type:         Package
Title:        SpatialGraph Class
Date:         2018-11-27
Imports:      igraph, methods, rgeos, shape, sp, splancs
Author:       Javier Garcia-Pintado
Maintainer:   Javier Garcia-Pintado <jgarciapintado@marum.de>
Description:  Provision of the S4 SpatialGraph class built on top of objects provided by 'igraph' and 'sp' packages, and asso
License:      GPL (>=2)
URL:          https://github.com/garciapintado/SpatialGraph

```

Index of help topics:

SpatialGraph	Create a SpatialGraph object
SpatialGraph-class	Class "SpatialGraph"
SpatialGraph-package	SpatialGraph Class
attSGe	Add or Modify attributes in SpatialGraph edges
distSGv	Calculate the distance slot in a SpatialGraph
explodeSLDF	Explode Lines in a SpatialLinesDataFrame

pointLineD	Euclidean distance from a set of points to a line segment
pointOnLine	Snap a points to a line
pointOnSegment	Snap a points to a segment
pointPolylineD	closest points in a polyline to a set of points
pointsToLines	Snap a set of points to a set of lines
polylineChainage	Obtain the chainage of nodes along a polyline
polylineLength	Obtain the length of a polyline
revSGe	Reverse Lines in a SpatialGraph
rotation	Rotate 2D points
routeSDG	Accumulate sources/sinks along a directed SpatialGraph
sg2igraph	Map a SpatialGraph into an igraph
sgChVIDs	Change vertex IDs in a SpatialGraph
sl2sg	map a SpatialLinesDataFrame into a SpatialGraph
splitPolyline	Split a polyline into a number of transects
splitSLDF	Split 1-Line Lines in a SpatialLines or a SpatialLinesDataFrame by intersection with a point dataset
textSGe	Label edges in a SpatialGraph plot

see the documentation of the function `sl2sg` in this package to get a start

### Author(s)

Javier Garcia-Pintado

Maintainer: Javier Garcia-Pintado <jgarciapintado@marum.de>

### References

The first published application of this package is Garcia-Pintado, J. et al. (2015). Satellite-supported flood forecasting in river networks: a real case study. *J. Hydrol.* 523, 705-724.

---

attSGe

*Add or Modify attributes in SpatialGraph edges*

---

### Description

Add or Modify attributes in SpatialGraph edges

### Usage

```
attSGe(SG, att, eID, val, default)
```

**Arguments**

SG	<a href="#">SpatialGraph</a>
att	name of the field [column] in the edge dataframe to be added/modified
eID	edge identifiers [row.names of the edge data.frame]
val	values corresponding the eID above
default	default values for edges not considered in eID above

**Value**

A [SpatialGraph](#)

---

distSGv	<i>Calculate the distance slot in a SpatialGraph</i>
---------	--

---

**Description**

Calculate the distance slot in a [SpatialGraph](#). This is done via a call to the library `igraph`, which does the calculation. Distances are undirected.

**Usage**

```
distSGv(SG, getpath = FALSE)
```

**Arguments**

SG	<a href="#">SpatialGraph</a>
getpath	boolean. Whether to calculate the SG@path slot

**Value**

A [SpatialGraph](#) with the slot `dist` (and `path` if requested) recalculated

---

explodeSLDF	<i>Explode Lines in a SpatialLinesDataFrame</i>
-------------	---

---

**Description**

explode Lines in a `SpatialLinesDataFrame`, so that each single Line, within each Lines slot, is upgraded as a new 1-Line Lines slot

**Usage**

```
explodeSLDF(SLDF, FID)
```

**Arguments**

SLDF	a SpatialLinesDataFrame
FID	if not NULL, field name, within the attribute table considered as additional unique identifier, so that incremental numeric values will added to this field to avoid duplicate values

**Value**

a SpatialLinesDataFrame

---

pointLineD	<i>Euclidean distance from a set of points to a line segment</i>
------------	--

---

**Description**

pointLineD returns a list with a number of components from a points to line segment analysis

**Usage**

```
pointLineD(xy, xyp)
```

**Arguments**

xy	2 x 2 [x,y] matrix defining the start and end of the segment
xyp	p x 2 [x,y] matrix with a point set

**Details**

pointLineD conduct a detailed points to segment distance analysis, returned as a list

**Value**

A list with the input components xy and xyp, and the additional components: d, point-line distance (distance between the points in xyp and their perpendicular projections of the line); dc, diferential chainage over [x0,y0] (> 0 if the projection goes in the segment direction); cross, boolean vector indicating whether the perpendicular projection of the points crosses the segment, or not

**See Also**

[Spatial-class](#)

---

pointOnLine                      *Snap a points to a line*

---

**Description**

This function snaps a point to a line based on the minimum distance between the point and the line

**Usage**

```
pointOnLine(cool, coop)
```

**Arguments**

cool	2-col matrix giving the coordinates of the line
coop	2-length vector representing the point

**Value**

A 4-length vector, with 'x','y' [coordinates of the point snapped to the line], 'd' [distance from the input point to the new snapped point], and 'chain' [accumulated along-line distance from the starting of the line to the snapped point]

**Author(s)**

Javier Garcia-Pintado

**See Also**

[Spatial-class](#)

---

pointOnSegment                      *Snap a points to a segment*

---

**Description**

This function snaps a point to a segment based on the minimum distance between the point and the segment

**Usage**

```
pointOnSegment(s, p)
```

**Arguments**

s	[2,2] matrix giving the coordinates of the line, one point per row
p	2-length vector representing the point

**Value**

A 4-length vector, with 'x','y' [coordinates of the point snapped to the segment], 'd' [distance from the input point to the new snapped point], and 'chain' [distance from the starting of the segment to the snapped point]

**Author(s)**

Javier Garcia-Pintado

**See Also**

[Spatial-class](#)

---

pointPolylineD	<i>closest points in a polyline to a set of points</i>
----------------	--

---

**Description**

pointPolylineD returns a list with a number of components from a points to polyline analysis

**Usage**

```
pointPolylineD(xy, xyp)
```

**Arguments**

xy	n x 2 [x,y] matrix defining the polyline
xyp	p x 2 [x,y] matrix with a point set

**Details**

pointPolylineD conducts a detailed points to polyline distance analysis. First the distance from the set of points to the lines defined by every single segment in the polyline is obtained by successive calls to pointLineD, then the distance to every single node in the polyline are also obtained. The lower distance is chosen.

**Value**

A data.frame with the columns: inode is the index of the first node in the closest segment to each point, x0 and y0 are the corresponding coordinates of those nodes, xc and yc are the coordinates of the point in the polyline closest to each point in xyp, these may be but are not necessarily one the polyline nodes, dis is the distance from each point to the polyline, chain0 is the chainage of x0,y0 with the polyline, and dc is the differential chainage from xc,yc to x0,y0

**See Also**

[Spatial-class](#)

---

`pointsToLines`*Snap a set of points to a set of lines*

---

**Description**

This function snaps a set of points to a set of lines based on the minimum distance of each point to any of the lines

**Usage**

```
pointsToLines(points, lines, withAttrs = TRUE, withDis = TRUE, withChain = TRUE)
```

**Arguments**

<code>points</code>	An object of the class <code>SpatialPoints</code> or <code>SpatialPointsDataFrame</code> , or a 2-col matrix of [x,y] coordinates
<code>lines</code>	An object of the class <code>SpatialLines</code> or <code>SpatialLinesDataFrame</code>
<code>withAttrs</code>	Boolean value for preserving (TRUE) or getting rid (FALSE) of the original point attributes. Default: TRUE. This parameter is optional
<code>withDis</code>	Boolean value for including distance from source points to snapped-to-lines points
<code>withChain</code>	Boolean value for including the chainage of the snapped points in their corresponding lines

**Value**

A `SpatialPointsDataFrame` object as defined by the R package 'sp'. This object contains the snapped points, therefore all of them lie on the lines. The returned object contains the fields 'lid', 'eID', and 'chain', providing information about the relationship between the source data points, the snapped data points, and its location within the network: 'lid', and 'eID' are the line index and line ID, respectively, of the lines in which the new snapped points lie; 'dis' is the distance between the input points and the snapped points, and 'chain' is the chainage of the snapped point within the corresponding line

**Author(s)**

Javier Garcia-Pintado

**See Also**

[Spatial-class](#)



---

polylineChainage      *Obtain the chainage of nodes along a polyline*

---

**Description**

Obtain the chainage of nodes along a polyline [2-col matrix]

**Usage**

polylineChainage(xy)

**Arguments**

xy                    a 2-column matrix representing the polyline nodes

**Details**

polylineChainage calculates a vector of chainage values [along-polyline distances] from each node in a polyline to the initial node

**Value**

A vector

**See Also**

[polylineLength](#)

---

polylineLength      *Obtain the length of a polyline*

---

**Description**

Obtain the length a polyline [2-col matrix]

**Usage**

polylineLength(xy)

**Arguments**

xy                    a 2-column matrix representing the polyline nodes

**Details**

polylineLength calculates the [along-polyline] length of the polyline

**Value**

A scalar

**See Also**

[polylineChainage](#)

---

 revSGe

*Reverse Lines in a SpatialGraph*


---

**Description**

A [SpatialGraph](#) contains a `SpatialLinesDataFrame`, describing the network topology. The input `eID` indicates the identifiers of a set of lines (edges) in the network to be reversed. Note `eID` does not refer to the line index within `SG@e`, but to the Feature Identifiers, as extracted from `row.names(SG@e@data)`

**Usage**

```
revSGe(SG, eID)
```

**Arguments**

<code>SG</code>	<code>SpatialGraph</code>
<code>eID</code>	vector of Feature Identifiers for lines to be reversed

**Details**

Note `eID` does not refer to the line index within `SG@e`, but to the Feature Identifiers, as extracted from `row.names(SG@e@data)`. Accordingly to the reversed coordinates, the corresponding fields `["v0","v1"]`, are interchanged.

**Value**

A [SpatialGraph](#)

---

rotation	<i>Rotate 2D points</i>
----------	-------------------------

---

**Description**

rotate points, counterclockwise for positive angles, and clockwise for negative ones

**Usage**

```
rotation(coords, radian)
```

**Arguments**

coords	2-col matrix of [x,y] coordinates
radian	rotation angle

**Value**

a 2-col matrix with the points rotated around [0,0]

---

routeSDG	<i>Accumulate sources/sinks along a directed SpatialGraph</i>
----------	---

---

**Description**

Assume a SpatialGraph is directed and conduct an accumulation of source/sink values at nodes across the network. The accumulation assumes no delay in transmission

**Usage**

```
routeSDG(SDG, FUN='cumsum', ifld='inflow')
```

**Arguments**

SDG	SpatialGraph, assumed as directed
FUN	name of a function to be applied for the routing
ifld	name on the field in the SpatialPointDataFrame vertex slot to be used used as source/sink

**Details**

The SpatialGraph, used as input, must have the ifld field to be used as input, in the vertices slot v (a SpatialPointsDataFrame). The accumulated output is provided as the new field ofld in v. The edges slot e serves to route the input across the network

**Value**

A SpatialGraph with the added ofId field in the vertex slot

---

sg2igraph

*Map a SpatialGraph into an igraph*

---

**Description**

The vertex and edge information in a SpatialGraph is mapped into an igraph object

**Usage**

```
sg2igraph(sg, directed=FALSE)
```

**Arguments**

sg	SpatialGraph
directed	whether the resulting igraph is directed

**Details**

It is assumed that the SpatialGraph, used as input, is correct (i.e.g all records in sg@e@data have the two first field correctly identifying the field 'ID' in sg@v. It is also assumed that the sg@e@data data.frame has the fields div and len. These two are highly useful to conduct network operations on the resulting igraph

**Value**

An igraph

---

sgChVIDs

*Change vertex IDs in a SpatialGraph*

---

**Description**

Change the field "ID" in the vertex slot, v, of a [SpatialGraph](#). The fields v0 and v1 of the edge slot, e, are accordingly updated

**Usage**

```
sgChVIDs(obj, IDa, IDp = NULL)
```

**Arguments**

obj	A <a href="#">SpatialGraph</a> object
IDa	A vector indicating the updated vertex IDs
IDp	A vector indicating the prior vertex IDs

**Details**

If IDp is not provided, it is assumed that the vector of updated indexes is sorted equally to the order in which the vertices are stored in the slot `v` of the [SpatialGraph](#). If IDp is provided, the mapping IDp -> IDa is used for reclassifying the vertices.

**Value**

A [SpatialGraph](#) object

---

sl2sg	<i>map a SpatialLinesDataFrame into a SpatialGraph</i>
-------	--

---

**Description**

This function is the major workhorse to map an input `SpatialLinesDataFrame`, as defined in the package `sp`, into a `SpatialGraph` by using the spatial connectivity. Input is first exploded by using [explodeSLDF](#), and then all vertices in the `SpatialGraph` are automatically generated according to crossings in the input polylines.

**Usage**

```
sl2sg(SL, clipd = NULL, getdist = TRUE, getpath = FALSE)
```

**Arguments**

SL	<code>SpatialLinesDataFrame</code> as defined in package <code>sp</code>
clipd	distance threshold for clipping features, If <code>NULL</code> , a value of <code>1.0E-04</code> of the domain side size is used
getdist	calculate the <code>dist</code> slot in the returned <code>SpatialGraph</code>
getpath	calculate the <code>path</code> slot in the returned <code>SpatialGraph</code>

**Details**

A `SpatialGraph` is generated

**Value**

A `SpatialGraph`

**Author(s)**

Javier Garcia-Pintado, e-mail: <j.garcia-pintado@marum.de>

**Examples**

```

# x y
# create list of Line objects
if (1 > 2) {
  library(sp)
  library(SpatialGraph)
  zz <- list()
  zz[[1]] <- Line(matrix(
    c(661750, 4229150,
      662650, 4229450,
      663550, 4227650,
      663550, 4226850), ncol=2, byrow=TRUE))
  zz[[2]] <- Line(matrix(
    c(660250, 4229650,
      661050, 4226450,
      662550, 4225350,
      664850, 4225850,
      664650, 4229150,
      662350, 4228850), ncol=2, byrow=TRUE))
  # upgrade Line as Lines
  for (i in 1:length(zz)) {
    zz[[i]] <- Lines(list(zz[[i]]), ID=i)
  }
  # as SpatialLines
  SL <- sp::SpatialLines(zz)
  # as SpatialGraph including path calculation
  SG <- sl2sg(SL, getpath=TRUE)

  plot(SL, axes=TRUE)
  points(SG@v, cex=2)
  lines(SG@e, lwd=2)
  points(SG@v, cex=2, col='grey', pch=19)
  text(SG@v, labels=SG@v$ID)
  # label edges and directions
  textSGe(SG)
  # show a distance matrix between nodes
  SG@dist
  # show path from node 1 to 3
  SG@path[1,3]
}

```

**Description**

A SpatialGraph object is created

**Usage**

```
SpatialGraph(v, e, dist = NULL, path = NULL)
```

**Arguments**

v	SpatialPointsDataFrame
e	SpatialLinesDataFrame
dist	along-network (symmetric) distance matrix
path	matrix of lists with paths corresponding to dist. While distances between vertex couples are symmetric, the path matrix is not symmetric as individual path to from source vertex to destination vertex. Each list in the matrix has two S3 components (v,e) describing vertices (including bounds) and edges along the path. Thus it is always one less edge than then number of vertices in the path

**Value**

SpatialGraph returns an object of class [SpatialGraph-class](#)

---

SpatialGraph-class	<i>Class "SpatialGraph"</i>
--------------------	-----------------------------

---

**Description**

Class for spatial networks

**Objects from the Class**

Objects can be created by calls to the function [SpatialGraph](#)

**Slots**

**v:** Object of class "SpatialPointsDataFrame", whose data.frame must contain the "ID" field as unique identifier

**e:** Object of class "SpatialLinesDataFrame", whose data.frame must contain the fields v0 and v1 matching the unique identifiers "ID" in the slot v data.frame

**dist:** Matrix, representing the undirected along-graph distance between all vertices in the network

**path:** list with variable length arrays describing the minimum distance path between vertices

**Author(s)**

Javier Garcia-Pintado, e-mail: <j.garcia-pintado@reading.ac.uk>

---

splitPolyline	<i>Split a polyline into a number of transects</i>
---------------	--

---

**Description**

splitPolyline returns a list with a number of transects along a polyline

**Usage**

```
splitPolyline(xy, xyp, dmax)
```

**Arguments**

xy	2-column [x,y] matrix defining the polyline nodes
xyp	2-column [x,y] matrix with a point set
dmax	maximum distance between points in xy and the polyline, for these to be considered for poyline splitting

**Details**

splitPolyline obtain the closest points in a polyline to a given input set of points. Those closest points are used to divide the polyline in a number of transects. The individual transects are clipped to the input point dataset, so the different transects are continuous in space. Note that if the input points is quite appart from the polyline, the output sequece of transect may substantially differ form the input polyline at rupture zones

**Value**

A list in which each element is a matrix representing an individual polyline

**See Also**

[Spatial-class](#)

---

splitSLDF	<i>Split 1-Line Lines in a SpatialLines or a SpatialLinesDataFrame by intersection with a point dataset</i>
-----------	---

---

**Description**

splitSLDF divides the 1-Line Lines in the SpatialLines or the SpatialLinesDataFrame at intersections with the input point dataset

**Usage**

```
splitSLDF(SLDF, SPDF, dmax=NULL)
```



**Arguments**

SLDF	length-1 SpatialLinesDataFrame or SpatialLines object
SPDF	SpatialPointsDataFrame
dmax	maximum distance between points in SPDF and the polylines in SLDF, for these to be considered for poyline splitting

**Details**

splitPolyline obtain the closest points in the SpatialLinesDataFrame to a given input set of points. Those closest points are used to divide the polylines in a number of transects. The individual transects are clipped to the input point dataset, so the different transects are continuous in space. Note that if the input points is quite appart from the polyline, the output sequence of transects may substantially differ form the input polyline at rupture zones. The input parameter dmax is provided as a mean to avoid too strange splitting results. Setting dmax to a ver low value will reduce the spureous results, but also the input points need to be closer to the lines for the adequate recognition of splitting points

**Value**

A SpatialLinesDataFrame or a SpatialLines, according to the input

**See Also**

[Spatial-class](#)

---

textSGe

*Label edges in a SpatialGraph plot*

---

**Description**

A [SpatialGraph](#) contains a SpatialLinesDataFrame, describing the network topology. This function adds line IDs and direction arrows to an existing plot of a [SpatialGraph](#).

**Usage**

```
textSGe(SG, acol='wheat', tcol='navyblue', arr.length=0.4)
```

**Arguments**

SG	SpatialGraph
acol	color of the graph direction arrows
tcol	color of the text for graph edge IDs
arr.length	length of the direction arrows

**Value**

Arrows and edge IDs added to a [SpatialGraph](#) plot

# Index

## \*Topic **classes**

SpatialGraph, 14  
SpatialGraph-class, 15

## \*Topic **package**

SpatialGraph-package, 2

## \*Topic **spatial**

attSGe, 3  
distSGv, 4  
explodeSLDF, 4  
pointLineD, 5  
pointOnLine, 6  
pointOnSegment, 6  
pointPolylineD, 7  
pointsToLines, 8  
polylineChainage, 9  
polylineLength, 9  
revSGe, 10  
routeSDG, 11  
sg2igraph, 12  
sgChVIDs, 12  
sl2sg, 13  
SpatialGraph, 14  
SpatialGraph-class, 15  
splitPolyline, 16  
splitSLDF, 16  
textSGe, 17

## \*Topic **utilities**

attSGe, 3  
distSGv, 4  
explodeSLDF, 4  
pointLineD, 5  
pointOnLine, 6  
pointOnSegment, 6  
pointPolylineD, 7  
pointsToLines, 8  
polylineChainage, 9  
polylineLength, 9  
revSGe, 10  
rotation, 11

routeSDG, 11  
sg2igraph, 12  
sgChVIDs, 12  
sl2sg, 13  
splitPolyline, 16  
splitSLDF, 16  
textSGe, 17

attSGe, 3

distSGv, 4

explodeSLDF, 4, 13

pointLineD, 5  
pointOnLine, 6  
pointOnSegment, 6  
pointPolylineD, 7  
pointsToLines, 8  
polylineChainage, 9, 10  
polylineLength, 9, 9

revSGe, 10  
rotation, 11  
routeSDG, 11

sg2igraph, 12  
sgChVIDs, 12  
sl2sg, 13  
SpatialGraph, 4, 10, 12, 13, 14, 15, 17  
SpatialGraph-class, 15, 15  
SpatialGraph-package, 2  
splitPolyline, 16  
splitSLDF, 16

textSGe, 17